

Fifth Semester B.E. Degree Examination, June-July 2009

Digital Signal Processing

Time: 3 hrs.

Max. Marks:100

Note: Answer any FIVE full questions.

- 1 a. Define DFT of $x(n)$ and IDFT of $X(K)$. Find 4-point DFT of $x(n) = \cos(\pi n/4)$ and IDFT of $X(K) = \{2, 0, 2, 0\}$. (10 Marks)
- b. Find 4-point DFTs of $x(n) = \{1, 2, 1, 2\}$ and $h(n) = \{1, 0, 0, 0\}$. Therefrom, using linearity, find DFTs of $g(n) = \{4.2, 0.5, 0.20, 0.5\}$ and $f(n) = \{-3.8, 2, 1, 2\}$. (10 Marks)
- 2 a. $X(K)$, $Y(K)$ and $G(K)$ are 6-point DFTs of $x(n)$, $y(n)$ and $g(n)$ respectively. With $x(n) = \{0, 1, 2, 3, 4, 0\}$, find
 i) $y(n)$ if $Y(K) = W_2^K X(K)$, and
 ii) $g(n)$ if $G(K) = W_3^{2K} X(K)$ (08 Marks)
- b. The sequence $x(n) = \{1, 1, 1, 1, 3, 1, 1, 4, 2; 1, 1, 3, 1, 1, 1\}$ is filtered through a filter with impulse response $h(n) = \{1, -1\}$. Compute the output of the filter $y(n)$ using overlap-save method. Use 5-point circular convolution. (12 Marks)
- 3 a. Compute the 4-point DFTs of $g(n) = \{1, 0, 0, 1\}$ and $f(n) = \{0, 1, 1, 0\}$ using a single 4-point DFT computation. (08 Marks)
- b. Use Radix-2 DIF algorithms for DFTs and DIT algorithm for IDFT to find the circular convolution $y(n) = x(n) \otimes h(n)$ if $x(n) = \{1, 1, 1, 1\}$ and $h(n) = \{1, 2, 3, 4\}$. (12 Marks)
- 4 a. Compute the 8-point DFT of

$$x(n) = \begin{cases} n & 0 \leq n \leq 7 \\ 0 & \text{Otherwise} \end{cases}$$
 using radix-2 DIT FFT algorithm. Draw the corresponding SFG and label all variables according to your calculations. What is the speedup of this algorithm with respect to direct calculation? (14 Marks)
- b. What are the salient features of DSP processors? (06 Marks)
- 5 a. Distinguish between the following:
 i) Analog and Digital filters.
 ii) IIR and FIR systems
 iii) Recursive and Non-recursive structures. (08 Marks)
- b. The transfer function of an IIR system is given by

$$H(z) = \frac{1 + \frac{1}{4}z^{-1}}{(1 + \frac{1}{2}z^{-1})(1 + \frac{1}{2}z^{-1} + \frac{1}{4}z^{-2})}$$
 Determine the block diagram representations of the system corresponding to (i) direct form (ii) canonic form (iii) cascade form and (iv) parallel form of realizations. (12 Marks)

- 6 a. Draw the frequency characteristics of direct Chebyshev and inverse Chebyshev filters and mark all salient points. Describe the procedural steps used to design a low pass direct Chebyshev digital filter. (10 Marks)
- b. What is frequency transformation in the design of filters? The transfer function of a analog normalized LPF is $H(s) = \frac{1}{s^2 + s + 1}$. Using frequency transformation, determine
- TF of a LPF of cutoff frequency 10 rad/sec.
 - TF of a HPF of cutoff frequency 10 rad/sec. (10 Marks)
- 7 Define bilinear transformation. Use bilinear transformation to design a lowpass Butterworth digital filter to meet the following specifications:
- 3 dB cutoff frequency of 0.5π rad.
 - Stopband attenuation of at least 15 dB at 0.75π rad. (20 Marks)
- 8 a. Design a lowpass FIR filter to meet the following specifications:
- Cutoff frequency = 500 Hz,
 - Sampling frequency = 2000 Hz,
 - Filter order = 10
 - Filter length = 11. (12 Marks)
- b. Represent the FIR system described by the impulse response $H(n) = \delta(n) + \frac{1}{4}\delta(n-1) - \frac{1}{8}\delta(n-2) + \frac{1}{4}\delta(n-3) + \delta(n-4)$ in direct form and linear phase realization form. (08 Marks)